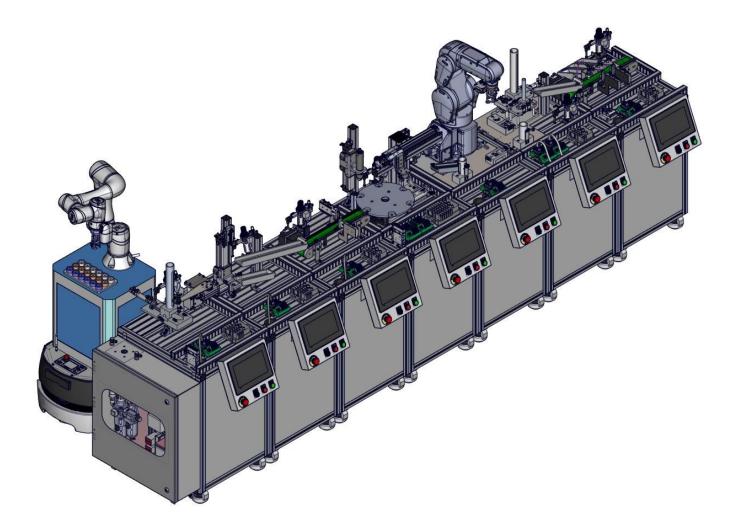


## Technical specifications of

## Modular Manufacturing System with Industry 4.0







Series MMS4

Cat No MMS4-01-01-A

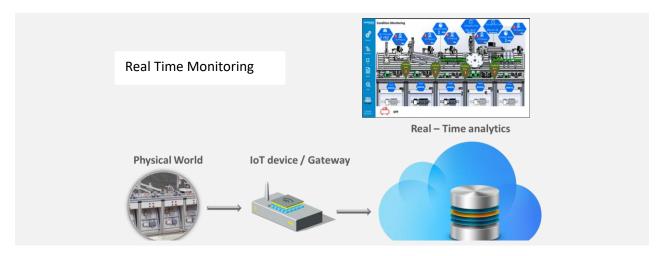
#### HIGHLIGHTS

- Modular System
- Energy Management
- Augmented Reality
- Manufacturing Execution System
- Overall Equipment Effectiveness (OEE)
- Management Information System
- Intelligent Maintenance system
- Autonomous Mobile Robot

#### **Learning Objectives**

- Learn about Industry 4.0 and Digitization of Value chain management.
- Understand & simulate the concept of various integration associated with Industry 4.0 such as Vertical, Horizontal, Integrated & Digital workforce.
- Understand the concepts of IIoT
- Learn about the architecture and design of IIoT systems.
- Understand the benefits of IIoT systems.
- Learn about the Remote monitoring of machine in real time
- Development of AR (Augmented Reality) applications
- Development of IIOT dashboard applications for different industry scenarios
- Development of SCADA Applications
- Understand the Data communication to cloud through IOT Gateway module
- Integration of AMR

#### **System Architecture & Function**

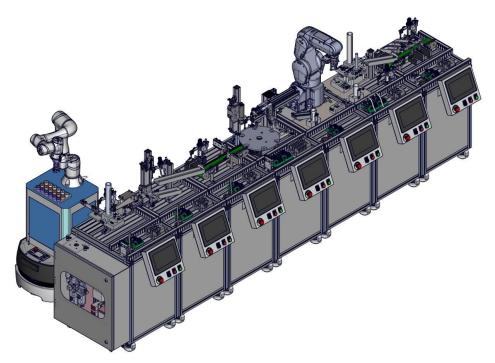






Series MMS4

Cat No MMS4-01-01-A



The above Image is for reference only.

#### Function

The Modular Manufacturing System with Industry 4.0 is a miniature factory which includes the industry standard processes such as Feeder, Inspection, Buffer, Process, Robot, Assembly and Sorting.

The MMS4.0 system produces orders executed from Manufacturing Execution System (MES) which is an interface for the complete value chain management.

The feeder station feeds the work pieces to the inspection station, in which the height of the work piece is measured, and only approved work pieces are allowed to the buffer station. The buffer station allows the work pieces one by one to the process station based on the demand received from the process station. The process station is performing drilling operation and further transfers the work pieces to the Robot and assembly station for assembly of Digital pressure gauge and quality testing. After testing the assembled work piece was transferred to sorting station. The sorting station segregates the work pieces based on the material type and color.





Series MMS4

Cat No MMS4-01-01-A

#### **System Features**

#### I. PRODUCTION MONITORING – ANDON

<u>[]::</u> ]	Production Monitoring	Production Start Production Stop	Parts Planned 10	Plant Janatics   Andom System
	Feeder	Inspection	Buffer	Process
	Part Count 11	Part Count 16	Part Count 0	Part Count 0
Production	Run Time (mins) 12807	Run Time (mins) 12807	Run Time (mins) 12807	Run Time (mins) 11509
	Total Downtime	Total Downtime 0	Total Downtime 0	Total Downtime 0
Maintenance	(mins)	(mins)	(mins)	(mins)
j_i	0 % OEE	O %	O %	0 % OEE
Ē				
MIS	Robot	Assembly	Sorter	
<u>Q</u>	Part Count 0	Part Count 0	Part Count 0	
Utility	Run Time (mins) 12807	Run Time (mins) 12807	Run Time (mins) 11512	
10:19 AM 5/30/2020	Total Downtime 0 (mins)	Total Downtime 0 (mins)	Total Downtime 0 (mins)	
Logout	<b>0</b> % OEE	0 % OEE	0 % OEE	

Production monitoring enables to understand the Productivity, Run Time & Down Time of the various machines available in the factory.

#### II. OVERALL EQUIPMENT EFFECTIVENESS - OEE

verall Equipment Effectivenes	5	]	Production Summary	
			Day Target	
	0 % 5 %	100 %	Total Produced Part Count	
OEE	A P	Q	Total Accepted Part Count	
- Overall Equipment Effectiveness A - Availabil	lity P-Performance Q-Quality		Total Rejected Part Count	
roduction Trends				
3 <u>-</u>				
2-		\		
0- I I 09:49:42 09:58:17	I I I 10:12:21 10:26:55 10:27:35	5 10:28:15 10:42:05	I I I 10:42:45 10:43:25 10:44:05	I I I 10:44:45 10:45:25 10:46:05
lachine Status				
	5 % OEE • Orrail Exponent Effectiveness A - Available roduction Trends	OEE A P - Cveral Equipment Effectiveness A - Availability P. Performance Q. Quality roduction Trends 3 - 0 0 0 0 0 0 0 0 0 0 0 0 0	5 %     100 %     5 %     P     100 %       • Oceral Equipment Effectiveness     A - Asalability     P. Performance     Q Quality	S %       IO0 %       S %       P       IO0 %       Q         OEE       A Auditability       P. Performance       Q       Quality       Day Target         Total Produced Part Count       Total Accepted Part Count       Total Accepted Part Count         Total Rejected Part Count       Total Rejected Part Count         roduction Trends       Image: Count of the second part of th

OEE (Overall Equipment Effectiveness) enables to measure and monitor the Performance, Quality & Availability of the Individual Machines

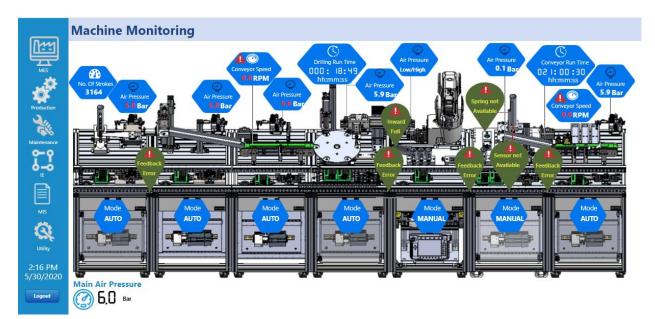




Series MMS4

Cat No MMS4-01-01-A

#### III. MACHINE MONITORING



Condition monitoring enables to monitor the real time data of the machine through which down time can be reduced.

#### IV. ENERGY MANAGEMENT

	Electrical Energy Consumption	Air Consumption	
	Бледу — — — — — — — — — — — — — — — — — — —	Air Pressure Compressor	
*	••••		
\$ <del>.</del> \$		0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
46 46 1031 AM 5/30/2020	Current	C Air Consumption	
5/30/2020			
		• • un to not hit all bit is all bit is all to all to all to all to all to all to bit is all bit is all bit is all bit is all to bit is all bit is all to be all bit is all to be all bit is all bits all bi	

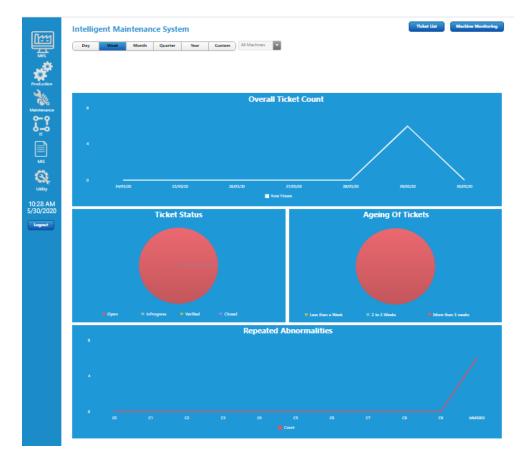
Energy management enables us to monitor and record the trend of Electrical and Air consumption of the machine.



Cat No MMS4-01-01-A

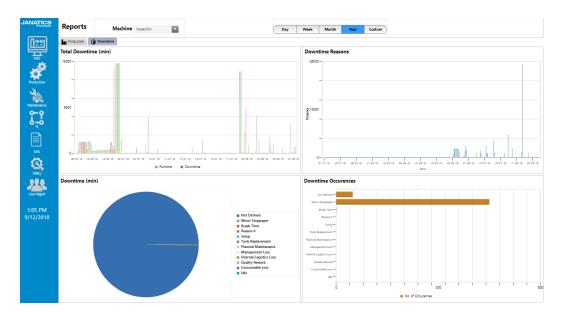
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#### V. INTELLIGENT MAINTENANCE SYSTEM



Intelligent Maintenance System enables us to monitor the Breakdowns.

#### VI. MANAGEMENT INFORMATION SYSTEM



Management information system enables to monitor the trend of Production and Downtime

**Technical specification** 





Series MMS4

Cat No MMS4-01-01-A

#### VII. AUGMENTED REALITY



The above Image is for reference only.

Augmented reality enables us to see Real-time data, assembly instruction, step by step instructions, and machine to design visualization.



**Series MMS4** 

Cat No MMS4-01-01-A

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#### Deliverables

S. No	Product Description	Product No.	Qty	UOM
1.	MMS4.0 Combination stations (1-2-3-4-6-7-5)	MMS40-C06-PXX	1	Set
1.1	MMS4.0 Control Unit	-	1	Nos
1.2	Feeder Station with HMI	-	1	Nos
1.3	Inspection Station with HMI & RFID	-	1	Nos
1.4	Buffer Station with HMI	-	1	Nos
1.5	Process Station with HMI	-	1	Nos
1.6	Robot station with HMI	-	1	Nos
1.7	Assembly station with HMI & RFID	-	1	Nos
1.8	Sorting Station with HMI	-	1	Nos
2	AMR with COBOT	-	1	Nos
3	PLC Software and Accessories	-	1	Set
4	Technical Documents	MMS40-C06-PXX-TD	1	Set
5	Work Piece set with RFID Tag	MMS-WP-S3-00	1	Set
6	Smart Manufacturing Execution System Application (1-year subscription)	JSMES-MMS4-001-01-03	1	Nos
7	Janatics Augmented Reality Application– JARA4.0 (1-year subscription)	JAR-MMS4-001-01-03	1	Nos

#### Note:

- 1. Apple I-Pad and Desktop PC / Laptop is mandatory for effective utilization of software application, which has to be purchased and preconfigured by end user@.
- 2. Smart Manufacturing Execution System Application & Janatics Augmented Reality Application is provided on SaaS basis with 1 years subscription, which shall be renewed after the term
- 3. Compressed Air connection with Max. 8 bar pressure to be provided by the customer.

	Desktop PC / Laptop		I-Pad
		Make	Apple
	Screen Size	11 Inch	
	Processor: 12th Generation Intel® Core™ i5 processor or Latest Hard disk: 512GB or above RAM : 8GB or above	RAM	16 GB
Configuration		Connectivity	Wi-Fi + Cellular
Configuration		Screen Size	11 Inch
		Memory	128 GB
		Accessories	Smart Folio for iPad Pro 11-
			inch

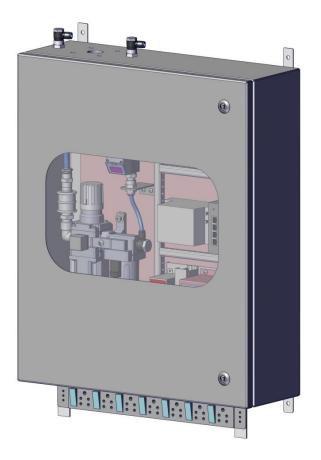




Series MMS4

Cat No MMS4-01-01-A

#### 1.1 MMS4.0 Control Cabinet



#### **Technical specification**

Ordering No	JPS1527
Size (L x W x H) in cm	60x83x20
Installation	Vertical
Medium	Electrical
Operating Voltage +/- 10%	230V
Power consumption	180 W (224 VA)
Material	CRCS





Cat No MMS4-01-01-A

#### Scope of supply:

S. No	Item with description	Qty
	Power supply Module	
1.	a) Power supply: Input voltage :230/115 V AC (47 – 63 Hz)	
	b) Output voltage: 24 V DC	
	c) Short-circuit-proof Output current: Maximum 3A	1
1.	d) Miniature circuit breaker DC voltage with max.5A current rating	
	e) RJ45 Cable (5 mtr. length) – 15no's	
	f) Terminal blocks	
	g) Power Connection cable: 3-pin plug with length of 1.3 Mtr.	
	Gate Way module:	
	a) Operating voltage: 24V DC	
2	b) Communication: Ethernet	1
2.	c) SD Card reader: Yes	1
	d) Programmable: JAVA 2, standard edition	
	e) Cellular: 3G with Antenna connector	
	Ethernet Switch:	
	a) No of Ports: 8 (Min.)	
-	b) Operating voltage: 24V DC/AC	2
3.	c) Communication: Ethernet	2
	d) Connector: RJ45, female	
	e) Transmission Speed: 10/100 Mbps	
	Energy Module:	
	a) Size: (L x W x H)- 300 x 190 x 100 mm (Min.)	
	Energy Meter:	
	a) Input Voltage: 110 - 415 V, programmable 1 Set	
	b) Input Frequency: 45 - 65 Hz.	
	Communication:	
	a) RS485 serial channel communication, Wi-Fi – Router	
	b) Operating Voltage: 5-40V	
4	c) Interface: Ethernet;100Mbps	
4.	d) Connection: RJ45	1
	e) Switching: RS232/485, automatic switching	
	f) Wireless Frequency Range: 2.412 GHz-2.484 GHz	
	Current Transformer:	
	a) Operating frequency: 50 Hz / 60 Hz	
	b) Rated Primary rating: 1A – 7500A.	
	c) Rated Secondary Output: 5A (Min.)	
	d) RJ45 Cable	
	e) Power Connection cable: 3-pin plug with length of 1.3 Mtr.	
5.	Air Monitoring Module:	1

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# Modular Manufacturing System Series MMS4

Cat No MMS4-01-01-A

	Flow Sensor	
	a) Flow range: 0-500 LPM	
	b) Operating Voltage: 24V DC	
	c) Analogue Output: 4-20 mA	
	Pressure Sensor	
	a) Operating Voltage: 24V DC	
	b) Pressure Range: 0-10 Bar	
	c) Analogue output: 1-5V	
	d) Digital Outputs: 2	
	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge and startup	
	valve:	
	a) Port size -1/4 inch	
	b) Flow rate – 500 l/min	
	c) Maximum supply pressure – 10 bar	
	d) Operating pressure- 6 bar	
	e) Filtering element grade – 40 μm	
	f) Minimum operating flow – 12 l/min	
	g) Filter Bowl capacity – 9 ml	
	h) Lubricator Bowl capacity – 20 ml	
	i) Connection for tube 8 mm dia. input and 8 mm dia. Output	
	j) Mounting – Socket head cap screw with M6 hammer head nut	
	PLC S7 -1200, CPU1212:	
	a) CPU 1214 PLC with	
	b) Digital Inputs- 8	
6.	c) Digital Outputs – 6	
0.	d) 1 x TCP/IP	
	e) Ethernet Communication port; 2 x AI 4 Channel Analog Input module	
	f) Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltage: 24 V DC	
	g) Short-circuit-proof Output current: Maximum 3A	
7.	RJ45 – RJ45 Cable - 2 Meter length	10





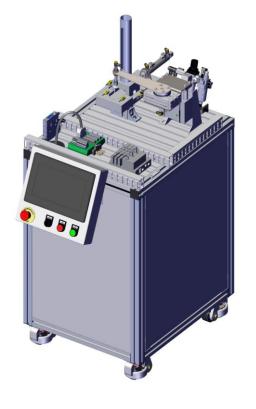
Series MMS4

Cat No MMS4-01-01-A

#### **1.2 Feeder Station with HMI**

#### Features

- Vacuum based 180° Rotary Pick and Place
- Energy saving vacuum ejector.
- Valve terminal with Fieldbus communication
- HMI control console
- Completely preassembled system
- Easy to use, and commission.
- Workbook with tasks and Solutions



#### Application

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors
- Vacuum

#### **Technical Specifications**

Model	MMS4
Size (in cm)	54x70x134
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	6-8 bar
Operating Voltage +/- 10%	230V AC, 50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, Plastic. etc.



Series MMS4

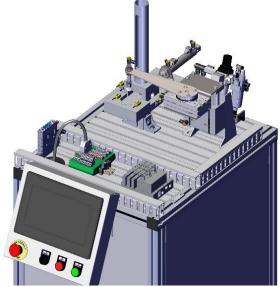
Cat No MMS4-01-01-A

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#### FUNCTION

The Feeder Station separates the components from the Stack Magazine and distributes the components one by one via rotary pick and place module for further processing. The Station consist of the following major parts.

- FRCLM module
- Dispensing module
- Rotary Pick and Place module
- Vacuum ejector module
- Valve module with Field bus communication
- I/O Interface Module
- Profile Table work bench
- PLC control
- HMI Control Console



The Dispensing module separates the jobs stacked in magazine tube with the help of pneumatic cylinder and provisions made for detecting the availability of jobs with optical sensors. Rotary Pick and Place module have a rotary actuator with an arm and suction cup to pick up work pieces and relocate them to positions from '0 degree to 180 degrees' on horizontal plane, so as to feed the subsequent stations. The end positions of all pneumatic actuators are detected by using Magnetic sensors. The feeder station consists of an aluminum anodized profile table, filter regulator and lubricator unit with pressure gauge, solenoid valve, one touch fittings mounted with suitable mountings for easy assembly and disassembly. Networking and signaling the subsequent stations. The PLC used for the station is capable of handling digital inputs and outputs, and it has Ethernet interface to communicate with PC for programming.





Cat No MMS4-01-01-A

#### **SCOPE OF SUPPLY:**

S. No	Item with description	Qty
	Horizontal Aluminum profile table:	
	a. (L x W x H)- 540 x 640 x 790 mm	
	b. Aluminum profile	
	Tabletop profile – 40 x 160 mm	
	Supporting profile- 40 x 40 mm	
1.	c. Grid spacing (From slot to slot) – 40 mm.	1
	d. Profile groove width – 8.3 mm	
	e. Leveling casters for quick setting and smooth movement	
	f. Profile plate connectors:	
	Length 55 mm, thickness 5mm	
	Mounting method M6 Socket head screw with M6 hammer head nut	
	I/O Interface module:	
2.	a. 25 Pin D-Sub connector interface board for interfacing valves and actuators	1
	b. 25 Pin D-Sub cable for establishing the connection between I/O module and PLC control	
	Valve Manifold with Field bus communication	
	a) L x W x H :120.5x119.4x29.8 mm	
	b) Grid spacing – 19 mm.	
	c) Mountable valve port size 1/8"	
	d) Silencers for reducing the dB level of exhausted air.	
	e) 5/2 Double solenoid pilot operated valve:	
	f) Material- Extruded aluminum with anodized	
3.	g) Voltage DC24V, Current consumption <120mA	1
	Solenoid valve	
	a) Size – 1/8''	
	b) Design – Spool type	
	c) Pressure range – 2 – 10 bar	
	d) Flow rate – 450 l / min	
	e) Manual override- Resetting	
	f) Fitted with 1/8'' flow control valve	
	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge and start up valve:	
	a) Port size -1/4 inch	
	b) Flow rate – 500 l/min	
	c) Maximum supply pressure – 10 bar	
	d) Operating pressure- 6 bar.	
4.	e) Filtering element grade – 40 μm	1
	f) Minimum operating flow – 12 l/min	
	g) Filter Bowl capacity – 9 ml	
	h) Lubricator Bowl capacity – 20 ml	
	i) Connection for tube 8 dia input and 8 dia output	
	j) Mounting – Socket head cap screw with M6 hammer head nut	



Cat No MMS4-01-01-A

**JANATICS** 

S. No	Item with Description	Qty
5.	<ul> <li>Stack Magazine module:</li> <li>a) Comprising of Miniature cylinder of dia 25 and stroke 80 mm Height: 516 mm, Width: 125 mm and Length: 390 mm</li> <li>b) Magnetic sensor for position sensing</li> <li>c) Light barrier Module: Type: Infra-red</li> <li>Sensing range: 2m</li> <li>Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current, Switch output: PNP, normally open/normally closed</li> <li>Output Protection: Protected against false pulse on closed contact.</li> <li>power- up, short-circuit protected</li> </ul>	1
6.	<ul> <li>Transfer Module:</li> <li>a) Cylinder rotation angle (rotary cylinder fitted with shock absorbers), 180 degrees (freely selectable)</li> <li>b) Compact guided cylinder dia 40 mm, Stroke - 50 mm</li> <li>c) Height: 325.5 mm, Width: 127 mm, Length: 223 mm</li> <li>d) Vacuum gripper module capable of handling 100gm</li> <li>e) Magnetic sensor for position sensing</li> </ul>	1
7.	<ul> <li>HMI Control console:</li> <li>a) 10" HMI, Make: Exor/Equivalent</li> <li>b) Cycle start push button –Green with illuminated</li> <li>c) Auto / Manual selector switch -Black</li> <li>d) Home position push button –Red with illuminated</li> <li>e) Emergency button -Red</li> </ul>	1
8.	Cable duct and accessories: a. Wire duct size 45x25 b. Fastening screws	
9.	<ul> <li>PLC control panel with S7 1200 PLC: CPU 1214</li> <li>a) Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltag24 V DC, short-circuit-proof Output current: Maximum 3A</li> <li>b) Miniature circuit breaker DC voltage with max.5A current rating</li> <li>c) Digital inputs-14,Digital outputs 10, Analog inputs 2 Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>d) 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>e) Cable ducts</li> <li>a) Power Connection cable:3pin plug with length of 1.3m</li> </ul>	1

**Series MMS4** 

Cat No MMS4-01-01-A

JANATICS

#### **1.3 INSPECTION STATION WITH HMI**

#### FEATURES

INDUSTRY

===

4.0

- LVDT based height measurement.
- Rod less Pneumatic drive
- RFID Tracking
- Valve terminal with Fieldbus communication
- HMI control console
- Completely preassembled system
- Easy to use, and commission
- Workbook with tasks and Solutions

#### APPLICATION

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors

#### **TECHNICAL SPECIFICATIONS**

Model	MMS4
Size (in cm)	68x64x135
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	6 - 8 bar
Operating Voltage +/- 10%	230V AC, 50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, Plastic.etc.





Series MMS4

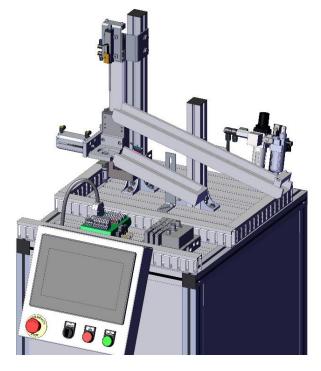
Cat No MMS4-01-01-A

#### FUNCTION

The Inspection station measures the height of the components received from its downstream station and transfers the correct and incorrect components to appropriate slides.

The Inspection station consists of the following.

- FRCLM module
- Measuring module
- Inspection slide module
- Valve module with Field bus communication
- I/O Interface Module
- Profile Table work bench
- PLC control
- HMI Control Console



Inspection station checks the jobs for height of about 25 mm using analog sensors and provisions have been made to detect work piece presence with the help of optical sensor. An arrangement is provided to transfer the right work piece by a slide to the next station and send faulty rejected work piece to the rejection bay.

The station consists of anodized profile table, filter regulator and lubricator unit with pressure gauge, on/off valve quick push connections and couplings mounted with suitable mountings for easy assembly and disassembly.





Cat No MMS4-01-01-A

#### **SCOPE OF SUPPLY:**

S. No	Item with description	Qty
	Horizontal Aluminum profile table:	
	a. (L x W x H)- 540 x 640 x 790 mm	
	b. Aluminum profile	
	Tabletop profile – 40 x 160 mm	
	Supporting profile- 40 x 40 mm	
1.	c. Grid spacing (From slot to slot) – 40 mm	1
	d. Profile groove width – 8.3 mm	
	e. Leveling casters for quick setting and smooth movement	
	f. Profile plate connectors:	
	Length 55 mm, thickness 5mm	
	Mounting method M6 Socket head screw with M6 hammer head nut	
2.	I/O Interface module:	1
	a. 25 Pin D-Sub connector interface board for interfacing valves and actuators	
	b. 25 Pin D-Sub cable for establishing connection between IO module and PLC control	
3.	Valve Manifold with Field bus communication	1
	a. L x W x H :120.5x119.4x29.8 mm	
	b. Grid spacing – 19 mm.	
	c. Mountable valve port size 1/8"	
	d. Silencers for reducing the dB level of exhausted air.	
	e. 5/2 Double solenoid pilot operated valve:	
	f. Material- Extruded Aluminum with anodized	
	g. Voltage DC24V, Current consumption <120mA	
	Solenoid valve	
	a. Size – 1/8''	
	b. Design – Spool type	
	c. Pressure range – 2 – 10 bar	
	d. Flow rate – 450 l / min	
	e. Manual override- Resetting	
	f. Fitted with 1/8" flow control valve	
4.	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge and start up	1
	valve:	
	a. Port size -1/4 inch	
	b. Flow rate – 500 l/min	
	c. Maximum supply pressure – 10 bar	
	d. Operating pressure- 6 bar	
	e. Filtering element grade – 40 μm	
	f. Minimum operating flow – 12 l/min	
	g. Filter Bowl capacity – 9 ml	
	h. Lubricator Bowl capacity – 20 ml	
	i. Connection for tube 8 dia input and 8 dia output	





Cat No MMS4-01-01-A

Measuring module:       a. Pneumatic Linear Drive of dia 25mm and Stroke 100 mm         b. LVD With Signal conditioner:       Maximum permissible applied voltage - 42V         Output: 4 - 20 mA       Overall length - 95 mm         c. Diffuse Sensor:       Type: Infra-red         Sensing range: 15mm       Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current Switch output: PNP, normally open/normally closed contact       1         Output Protection: Protected against false pulse on power-up, short-circuit. Protected       d. RFID sensor:         Read/write distance :15mm(min)       Supply Voltage:10 to 30V DC         Supply Voltage:10 to 30V DC       M8 Communication/ Power cable         6.       Approve and rejection Slide Module       1         HMI Control console:       a. 10" HMI Make: Exor/Equivalent       1         b. Cycle start push button –Green with illuminated.       c. Auto /Manual selector switch -Black       1         d. Home position push button -Red with illuminated       e. Emergency button -Red       1         Cable duct and accessories:       a. Wire duct size 45x25       1         b. Fastening screws       1       1         PLC control panel with AB PLC MicroLogix 1400:       a. Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltage: 24 V DC, short-circuit-proof Output current: Maximum 3A       b. Miniature circuit breaker DC voltage with max 5A current rating </th <th></th> <th>j. Mounting – Socket head cap screw with M6 hammer head nut</th> <th></th>		j. Mounting – Socket head cap screw with M6 hammer head nut	
b.       LVDT with signal conditioner: Maximum permissible applied voltage - 42V Output: 4 - 20 mA Overall length - 95 mm       1         c.       Diffuse Sensor: Type: Infra-red       1         5.       Sensing range: 15mm Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current Switch output: PNP, normally open/normally closed contact Output Protection: Protected against false pulse on power-up, short-circuit. Protected       1         6.       Approve and rejection Slide Module       1         7.       a. 10" HMI Make: Exor/Equivalent       1         7.       b. Cycle start push button -Green with illuminated. c. Auto /Manual selector switch -Black       1         6.       Approve and rejection Slide Module       1         7.       Cable duct and accessories: a. 10" HMI Make: Exor/Equivalent       1         8.       Cycle start push button -Green with illuminated       1         9.       Cable duct and accessories: a. Wire duct size 45x25       1         8.       a. Wire duct size 45x25       1         9.       PLC control panel with AB PLC MicroLogix 1400: a. Power supply: Input voltage: 230/115 V AC (47 - 63 Hz), Output voltage: 24 V DC, short- circuit-proof Output current: Maximum 3A       1         9.       Miniature circuit breaker DC voltage with max.5A current rating       1         9.       Miniature circuit breaker DC voltage with max.5A current rating       1			
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<ul> <li>circuit-proof Output current: Maximum 3A</li> <li>b. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>c. Digital inputs-20,Digital outputs 12, Analog inputs 4, Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>9. d. Analogue module: Analogue input(4-20mA)</li> <li>e. Terminal blocks</li> <li>f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>g. Cable ducts</li> <li>h. Power Connection cable:3pin plug with length of 1.3m</li> <li>i. IO link module</li> </ul>		PLC control panel with AB PLC MicroLogix 1400:	
<ul> <li>b. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>c. Digital inputs-20,Digital outputs 12, Analog inputs 4, Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>9. d. Analogue module: Analogue input(4-20mA)</li> <li>e. Terminal blocks</li> <li>f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>g. Cable ducts</li> <li>h. Power Connection cable:3pin plug with length of 1.3m</li> <li>i. IO link module</li> </ul>		a. Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltage: 24 V DC, short-	
<ul> <li>c. Digital inputs-20,Digital outputs 12, Analog inputs 4, Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>9. d. Analogue module: Analogue input(4-20mA)</li> <li>e. Terminal blocks</li> <li>f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>g. Cable ducts</li> <li>h. Power Connection cable:3pin plug with length of 1.3m</li> <li>i. IO link module</li> </ul>		circuit-proof Output current: Maximum 3A	
Mbit/s 9. d. Analogue module: Analogue input(4-20mA) 1 e. Terminal blocks f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm <sup>2</sup> g. Cable ducts h. Power Connection cable:3pin plug with length of 1.3m i. IO link module		b. Miniature circuit breaker DC voltage with max.5A current rating	
9.       d. Analogue module: Analogue input(4-20mA)       1         e.       Terminal blocks       1         f.       25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm²       1         g.       Cable ducts       1         h.       Power Connection cable:3pin plug with length of 1.3m       1         i.       IO link module       1		c. Digital inputs-20, Digital outputs 12, Analog inputs 4, Ethernet interface 1 x TCP/IP, 10	
<ul> <li>e. Terminal blocks</li> <li>f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>g. Cable ducts</li> <li>h. Power Connection cable:3pin plug with length of 1.3m</li> <li>i. IO link module</li> </ul>		Mbit/s	
<ul> <li>f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm<sup>2</sup></li> <li>g. Cable ducts</li> <li>h. Power Connection cable:3pin plug with length of 1.3m</li> <li>i. IO link module</li> </ul>	9.	d. Analogue module: Analogue input(4-20mA)	1
<ul><li>g. Cable ducts</li><li>h. Power Connection cable:3pin plug with length of 1.3m</li><li>i. IO link module</li></ul>		e. Terminal blocks	
<ul><li>h. Power Connection cable:3pin plug with length of 1.3m</li><li>i. IO link module</li></ul>		f. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm <sup>2</sup>	
<ul><li>h. Power Connection cable:3pin plug with length of 1.3m</li><li>i. IO link module</li></ul>		g. Cable ducts	
i. IO link module			
$\checkmark$ NUTINET OF INDUS, VOILAGE(V), Z, ZU-ZOVDC		<ul> <li>Number of Inputs, voltage(V): 2, 20-28VDC</li> </ul>	

Series MMS4

Cat No MMS4-01-01-A

JANATICS

#### **1.4 BUFFER STATION WITH HMI**

#### **FEATURES**

INDUSTRY

===

4.0

- DC Brushless motor conveyor
- Twin Piston rod cylinders
- Valve Terminal with Field bus communication
- HMI control console
- Completely preassembled system
- Easy to use, and commission.
- Workbook with tasks and Solutions



#### APPLICATION

These Mechatronics systems are fully functional models of actua applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors

#### **TECHNICAL SPECIFICATIONS**

Model	MMS4
Size (in cm)	55x64x106
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	6 - 8 bar
Operating Voltage +/- 10%	230V AC, 50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, Plastic. etc.



Series MMS4

Cat No MMS4-01-01-A

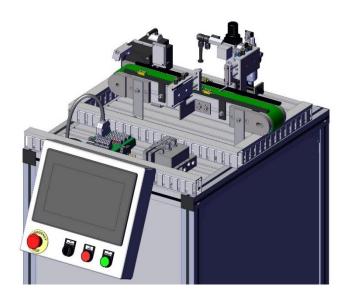
JANATICS

#### FUNCTION

Buffer Station ensures steady flow of components to the process station by allowing one component at a time for processing. It can store up to 5 work pieces at a time and if the count has exceeded 5, it communicates with the downstream stations to STOP the processing activities until the count reaches 5.

Buffer Station consists of the following.

- FRCLM module
- Conveyor module
- Valve module with Fieldbus communication
- I/O Interface Module
- Profile Table work bench
- PLC control
- HMI Control Console



Buffer station can buffer up to 5 jobs. The buffering process should be controlled by a separator using upstream and downstream light barriers sensors. Retro reflective sensor detects the inserted job and keeps tag on the nos. of jobs buffered precisely while the separator module passes the job to the next station if the transfer point is free. The buffer station waits for the signal from the downstream station & as soon as it receives the signal is transferred. The end position of all pneumatic actuators is detected by using Magnetic sensors.

The station consists of anodized profile plate, filter regulator and lubricator unit with pressure gauge, on/off valve quick push connections and couplings mounted with suitable mountings for easy assembly and disassembly.





Cat No MMS4-01-01-A

#### **SCOPE OF SUPPLY:**

S. No	Item with description	Qty
	Horizontal Aluminum profile table:	
	a. (L x W x H)- 540 x 640 x 790 mm	
	b. Aluminum profile	
	Tabletop profile – 40 x 160 mm	
	Supporting profile- 40 x 40 mm	
1.	c. Grid spacing (From slot to slot) – 40 mm	1
	d. Profile groove width – 8.3 mm	
	e. Leveling casters for quick setting and smooth movement	
	f. Profile plate connectors:	
	Length 55 mm, thickness 5mm	
	Mounting method M6 Socket head screw with M6 hammer head nut	
2.	I/O Interface module:	1
	a. 25 Pin D-Sub connector interface board for interfacing valves and actuators	
	b. 25 Pin D-Sub cable for establishing connection between IO module and PLC	
3.	Valve Manifold with Field bus communication	1
	a. L x W x H :104.5x119.4x29.8 mm	
	b. Grid spacing – 19 mm.	
	c. Mountable valve port size 1/8"	
	d. Silencers for reducing the dB level of exhausted air.	
	e. 5/2 Double solenoid pilot operated valve:	
	f. Material- Extruded Aluminum with anodized	
	g. Voltage DC24V, Current consumption <120mA	
	Solenoid valve	
	a. Size – 1/8 ''	
	b. Design – Spool type	
	c. Pressure range – 2 – 10 bar	
	d. Flow rate – 450 l / min	
	e. Manual override- Resetting	
	f. Fitted with 1/8" flow control valve	
4.	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge and start up	1
	valve:	
	a. Port size -1/4 inch	
	b. Flow rate – 500 l/min	
	c. Maximum supply pressure – 10 bar	
	d. Operating pressure- 6 bar	
	e. Filtering element grade – 40 μm	
	f. Minimum operating flow – 12 l/min	
	g. Filter Bowl capacity – 9 ml	
	h. Lubricator Bowl capacity – 20 ml	





Cat No MMS4-01-01-A

	i. Connection for tube 8 dia input and 8 dia output	
	j. Mounting – Socket head cap screw with M6 hammer head nut	
	Conveyor Module:	
	a. Flat belt conveyor with overall length of 500mm	
	b. Conveyor to be driven by 24V DC motor of reputed make.	
	c. Conveyor to be provided with electronic drive unit for regulating the speed, reversing the direction and other function.	
	<ul> <li>Separator Module:</li> <li>Comprising of 2 pneumatic cylinders of dia 25 mm and stroke 25mm</li> </ul>	
	e. Retro reflective -Photo electric sensor (Upstream):	
	i. Type: Infra-red	
	ii. Sensing range: 2m	
	<ul> <li>Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @20mA max current</li> </ul>	
	iv. Switch output: PNP, normally open/normally closed contact	
	<ul> <li>V. Output Protection: Protected against false pulse on power-up, short circuit protected.</li> </ul>	
5.	f. Thru beam -Photo electric sensor (Downstream):	1
	i. Type: Infra-red	
	ii. Sensing range: 2m	
	iii. Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current	
	iv. Switch output: PNP, normally open/normally closed contact	
	v. Output Protection: Protected against false pulse on power-up, short-circuit protected.	
	g. Diffuse Sensor - Photo electric:	
	i. Type: Infra-red	
	ii. Sensing range: 15mm	
	iii. Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current	
	iv. Switch output: PNP, normally open/normally closed contact	
	v. Output Protection: Protected against false pulse on power-up, short-circuit	
	protected	
	HMI Control console:	
	a. 10" HMI Make Exor/Equivalent	
c	b. Cycle start push button –Green with illuminated.	1
6.	c. Auto /Manual selector switch -Black	1
	d. Home position push button –Red with illuminated	
	e. Emergency button -Red	
7.	Cable duct and accessories: a. Wire duct size 45x25	1
	a. Wire duct size 45x25 PLC control panel with S7 1200 PLC: CPU 1214	
0		4
8.	short-circuit-proof Output current: Maximum 3A	1
	b. Miniature circuit breaker DC voltage with max.5A current rating	
	c. Digital inputs-14, Digital outputs 10, Analog inputs 2Ethernet interface 1 x TCP/IP, 10	





Cat No MMS4-01-01-A

	Mbit/s	
d.	Terninal blocks	
e.	25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm <sup>2</sup>	
f.	Cable ducts	
g.	Power Connection cable:3pin plug with length of 1.3m	
h.	Optocoupler	

Series MMS4

#### Cat No MMS4-01-01-A

JANATICS

#### 1.5 PROCESS STATION WITH HMI FEATURES

- 6 stage Rotary Indexing table
- Rod less Pneumatic drive
- Pneumatic motor

INDUSTRY

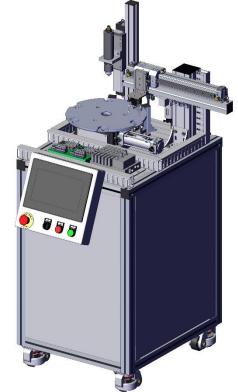
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4.0

- Pneumatic based linear Pick and Place
- Valve Terminal with Field bus communication
- HMI control console
- Completely preassembled system
- Easy to use, and commission.
- Workbook with tasks and Solutions

#### APPLICATION

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as



- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors
- Vacuum

#### **TECHNICAL SPECIFICATIONS**

Model	MMS4
Size (in cm)	72x64x141
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	6-8 bar
Operating Voltage +/- 10%	230V AC, 50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, Plastic. etc.





Series MMS4

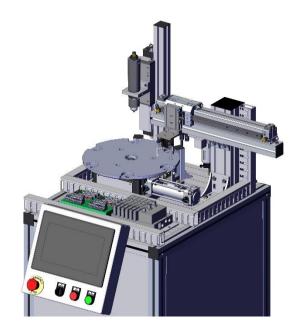
Cat No MMS4-01-01-A

#### FUNCTION

The Process Station performs mechanical operations like Drilling, Inspection etc on a pneumatically driven rotary indexing table and transfers the work piece via Pick and place module to downstream Station.

The Process Station consists of the following.

- FRCLM module
- Rotary Indexing table module
- Drilling module
- Pick and Place module.
- Valve module with Fieldbus communication
- I/O Interface Module
- Profile Table work bench
- PLC control
- HMI Control Console



The processing station is capable of processing machining operations like drilling/grinding/polishing using pneumatically driven indexing table and electrically driven drilling machine using the six processing locations on the indexing table. A pneumatic linear drive module moves the drill unit up and down. Provisions can be made to detect the position of hole and the depth of hole using sensors. The station is provided with a Pick and place module to transfer the job the next station.

The station should consist of anodized profile plate, filter regulator and lubricator unit with pressure gauge, on/off valve quick push connections and couplings mounted with suitable mountings for easy assembly and disassembly.





Cat No MMS4-01-01-A

#### **SCOPE OF SUPPLY:**

S. No	Item with description	Qty
	Horizontal Aluminum profile table:	
	a. (L x W x H)- 540 x 640 x 790 mm	
	b. Aluminum profile	
	Tabletop profile – 40 x 160 mm	
	Supporting profile- 40 x 40 mm	
1.	c. Grid spacing (From slot to slot) – 40 mm.	1
	d. Profile groove width – 8.3 mm	
	e. Leveling casters for quick setting and smooth movement	
	f. Profile plate connectors:	
	Length 55 mm, thickness 5mm	
	Mounting method M6 Socket head screw with M6 hammer head nut	
2.	I/O Interface module:	
	a. 25 Pin D-Sub connector interface board for interfacing valves and actuators	1
	b. 25 Pin D-Sub cable for establishing connection between IO module and PLC control	
3.	Valve Manifold with Field bus communication	
	a. L x W x H :168.5x119.4x29.8 mm	
	b. Grid spacing – 19 mm.	
	c. Mountable valve port size 1/8"	
	d. Silencers for reducing the dB level of exhausted air.	
	e. 5/2 Double solenoid pilot operated valve:	
	f. Material- Extruded Aluminum with anodized	
	g. Voltage DC24V, Current consumption <120mA	1
	Solenoid valve	
	a. Size – 1/8 "	
	b. Design – Spool type	
	c. Pressure range – 2 – 10 bar	
	d. Flow rate – 450 l / min	
	e. Manual override- Resetting	
	f. Fitted with 1/8" flow control valve	
4.	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge and start up	
	valve:	
	a. Port size -1/4 inch	
	b. Flow rate – 500 l/min	
	c. Maximum supply pressure – 10 bar	1
	d. Operating pressure- 6 bar	
	e. Filtering element grade – 40 μm	
	f. Minimum operating flow – 12 l/min	
	g. Filter Bowl capacity – 9 ml	
	h. Lubricator Bowl capacity – 20 ml	





Cat No MMS4-01-01-A

	i. Connection for tube 8 dia input and 8 dia output	
	j. Mounting – Socket head cap screw with M6 hammer head nut	
6.	<ul> <li>Rotary indexing table module:</li> <li>a. Pneumatically driven rotary indexing table capable of handling load up to 50 kg</li> <li>b. Indexing table to be driven by cylinder of Ø 40 x 75 mm</li> <li>c. Indexing angle 60 degrees</li> <li>d. Indexing plate diameter-320 mm</li> <li>Diffuse Sensor:</li> <li>a. Type: Infra-red</li> <li>b. Sensing range: 15mm</li> <li>c. Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current</li> <li>d. Switch output: PNP, normally open/normally closed contact</li> <li>e. Output Protection: Protected against false pulse on power-up, short-circuit protected</li> </ul>	1
7.	<ul> <li>Drilling Module:</li> <li>a. Drilling machine to be mounted on a pneumatic linear drive of stroke. 100mm</li> <li>b. Pneumatic drilling machine: No-load Speed: 3000 rpm, Weight: 1.4 Kg</li> </ul>	1
8.	<ul> <li>Pick and Place module.</li> <li>a. Rod less cylinder – dia 25 mm x 250 mm stroke</li> <li>b. Aluminum profile pillar – 80 x 80 mm</li> <li>c. Rod less cylinder mounting profile- 40 x 40 mm</li> <li>d. Twin rod cylinder- 15 mm stroke length</li> <li>e. 3 jaw pneumatic gripper</li> </ul>	1
9.	<ul> <li>HMI Control console:</li> <li>a. 10" HMI Make: Exor</li> <li>b. Cycle start push button –Green with illuminated.</li> <li>c. Auto /Manual selector switch -Black</li> <li>d. Home position push button –Red with illuminated</li> <li>e. Emergency button -Red</li> </ul>	1
10.	Cable duct and accessories: a. Wire duct size 45x25 b. Fastening screws	1
11.	<ul> <li>PLC control panel with Mitsubishi PLC – FX Series:</li> <li>a. Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltage: 24 V DC, short-circuit-proof Output current: Maximum 3A</li> <li>b. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>c. Digital inputs-32, Digital outputs 32, Analog inputs 2, Ethernet interface 1x TCP/IP, 10 Mbit/s</li> <li>d. Terminal blocks</li> <li>e. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm2.</li> <li>f. Cable ducts</li> <li>g. Power Connection cable:3 pin plug with length of 1.3m</li> </ul>	1

Series MMS4

Cat No MMS4-01-01-A

JANATICS

#### **1.6 ROBOT STATION WITH HMI**

#### **FEATURES**

INDUSTRY

===

4.0

- 6 Axis Articulated Robot
- Servo operated.
- 4Kg Payload
- 1 Phase power supply
- Inbuilt servo controller
- HMI Control console
- Completely preassembled system
- Easy to use, and commission.
- Workbook with tasks and Solutions

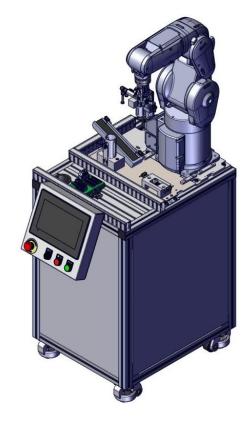
#### APPLICATION

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors
- Robotics

#### **Technical Specifications**

Model	MMS4
Size (in cm)	54x64x155
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	2-3 bar
Operating Voltage +/- 10%	230V AC, single phase 50HZ
Power consumption	1.9 KW (2.1KVA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, SS, Plastic .etc.



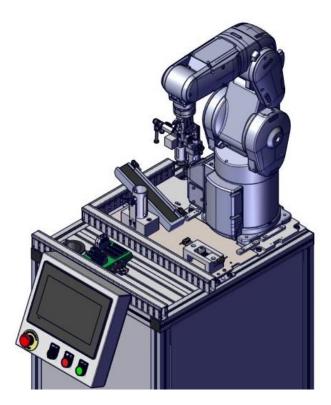




**Series MMS4** 

Cat No MMS4-01-01-A

FUNCTION



Robot station with the combination of assembly station assembles the incoming work piece with spring and digital sensor assembly and sends to downstream station.

Robot takes the work piece from the inward slide using parallel gripper and orients the component at orientation module and places the same in assembly area.

Robot picks and places the spring on to the work piece from the spring dispenser module and picks the digital sensor assembly from the Cap dispenser module and orients at orientation module. After orientation, robot test the digital sensor for quality check and approved work piece is assembled. If, the work piece is not approved then it is moved to the rejection bin. After assembling, the robot picks the assembled work pieces from the assembly location and sends the same to the downstream station through outward slide.



Series MMS4

Cat No MMS4-01-01-A

**JANATICS** 

#### SCOPE OF SUPPLY:

S. No	Item with description	
	Robot module: a. Make : Mitsubishi	
	b. Axes: 6c. Drive motor: All-axis servo motd. Maximum motion area: 515mm	or
1.	e.Maximum payload: 4kgf.Cycle time: 0.35secg.Position repeatability: ±0.02mm	1
		sensor signals, etc.)
	j.Maximum air pressure: 5bar maxk.Controller operating voltage: Single phase, 230	VAC
	Horizontal Aluminum profile table:a. (L x W x H): 540 x 640 x 790 mb. Aluminum profile: Tabletop profile -	- 40 x 160 mm
2.	c. Grid spacing (slot to slot) : 40 mm d. Profile groove width : 8.3 mm e. Profile plate connectors: : Length 55 mm, th	ickness 5mm crew & hammer head nut
3.	Filter Regulator Combination with Lubricator (FRL Unit) w valve:a. Port size: 1/4 inchb. Flow rate: 500 l/minc. Maximum pressure: 10 bard. Operating pressure: 6 bare. Filtering element grade: 40 μmf. Minimum operating flow: 12 l/ming. Filter Bowl capacity: 9 mlh. Lubricator Bowl capacity: 20 mli. Tube Connection: 8 dia input and 8 dia	vith pressure gauge and start up
4.	Storage module: Comprising of a storage block with assembly bins and	sensors 1
5.	Inward slide module: Comprising of a slide module with sensors.	
6.	Orientation module: Comprising of an orientation block with orientation sensors	





Cat No MMS4-01-01-A

7.	<ul> <li>HMI Control console:</li> <li>a. 10" HMI Make: Exor</li> <li>b. Cycle start push button –Green with illuminated.</li> <li>c. Auto /Manual selector switch -Black</li> <li>d. Home position push button –Red with illuminated</li> <li>e. Emergency button -Red</li> </ul>	1
8.	Controller module: Consists of Robot controller with I/O cables assembled on the aluminum. profile assembly	1
9.	<ul> <li>I/O interface module: <ul> <li>a. Input voltage :24V</li> <li>b. Output current: Maximum 3A</li> <li>c. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>d. Terminal blocks</li> <li>e. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm2.</li> <li>f. Cable ducts</li> <li>g. Power Connection cable:3pin plug with length of 1.3m</li> </ul> </li> </ul>	1
10.	Cable duct and accessories: a. Wire duct size 45x25 b. Fastening screws	1





Series MMS4

Cat No MMS4-01-01-A

#### **1.7 ASSEMBLY STATION WITH HMI**

#### FEATURES

- Pneumatic drives-based feeder system
- RFID Tracking
- Valve terminal with Field bus communication
- HMI Control console
- Completely preassembled system
- Easy to use, and commission
- Workbook with tasks and Solutions



#### **APPLICATION**

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors

#### **TECHNICAL SPECIFICATIONS**

Model	MMS4
Size (in cm)	54x64x115
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	2-3.5 bar
Operating Voltage +/- 10%	230V AC,50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, SS, Plastic. etc.





**Series MMS4** 

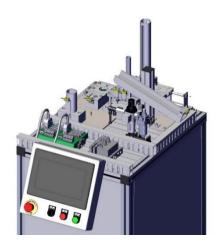
Cat No MMS4-01-01-A

#### FUNCTION

Assembly station is add-on module of Robot station. Cap dispensing module dispenses the digital sensor and spring dispensing module dispenses the spring required for assembly. The testing and assembly module allows the robot to test and assemble the work pieces. The outward module allows the assembled work pieces to move to the downstream station. Rejection module holds the rejected components/work pieces.

The Assembly Station consists of the following.

- Horizontal Profile Table work bench with castor wheels
- FRCLM Module
- Assembly and Testing module
- Cap dispenser module
- Spring dispenser module
- Outward slide module
- Rejection module
- HMI Control console
- PLC board assembly module
- I/O interface module
- Valve module with Fieldbus communication
- Cable duct with accessories



The station should consist of anodized profile table, filter regulator and lubricator unit with pressure gauge, on/off valve quick push connections and couplings mounted with suitable mountings for easy assembly and disassembly. Networking and signaling to the subsequent station for further processing should be done by establishing profinet communication between the PLC and robot controller. The robot controller used in this station should be capable of handling various digital inputs/output



Cat No MMS4-01-01-A

**JANATICS** 

#### **SCOPE OF SUPPLY:**

S. No	Item wit	h description	Qty
	Horizontal Aluminum profile table:		
1.	a. (L x W x H) : 54	0 x 640 x 790 mm	
	b. Aluminum profile	bletop profile – 40 x 160 mm	
	: Su	pporting profile- 40 x 40 mm	
	1 81 1	mm	1
	5	3 mm	
		ngth 55 mm, thickness 5mm	
	8	5 Socket head screw & hammer head nut	
	g. Leveling casters for quick setting and		
	Filter Regulator Combination with Lubrica	tor (FRL Unit) with pressure gauge and start up	
	valve:		
	a. Port size : 1/4 ir	ch	
	b. Flow rate : 500 l,	min	
	c. Maximum pressure : 10 ba	r	
2.	d. Operating pressure : 6 bar		1
	e. Filtering element grade : 40 μr	1	
	f. Minimum operating flow : 12 l/r	nin	
	g. Filter Bowl capacity : 9 ml		
	h. Lubricator Bowl capacity : 20 m		
		input and 8 dia output	
		ocket head screw & hammer head nut	
	Assembly and Testing module:		
	a. Assembly and Testing block with elect	rical assembly and sensor	
	b. RFID sensor		
3.	Read/write distance :15mm(min)		
	• Supply voltage: 10 to 30 V DC		
	M8 Communication/ Power cable		
	Cap dispenser module:		
4.	Consists of Machined dispenser mod	ule with sensors and Linear Motion rail and	1
	guide.		
	Spring dispenser module:		
5.	Consists of Machined dispenser modu	e with sensors and Linear Motion rail	1
	and guide.		
C	Outward slide module:		1
6.	Comprising of a slide module with sen	sors.	1
	Rejection module:		
7.	Comprising of a rejection block with a	bin and sensor.	1





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		1
8.	<ul> <li>HMI Control console:</li> <li>a. 10" HMI Make: Exor</li> <li>b. Cycle start push button –Green with illuminated.</li> <li>c. Auto /Manual selector switch -Black</li> <li>d. Home position push button –Red with illuminated</li> <li>e. Emergency button -Red</li> </ul>	1
9.	<ul> <li>PLC board assembly module:</li> <li>a. PLC control panel with S7 1200 PLC, CPU 1214</li> <li>b. Input voltage :230/115 V AC (47 – 63 Hz),</li> <li>c. Output voltage: 24 V DC, short-circuit-proof</li> <li>d. Output current: Maximum 3A</li> <li>e. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>f. Digital inputs-14</li> <li>g. Digital outputs 10</li> <li>h. Analog inputs 2Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>i. Terminal blocks</li> <li>j. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm2.</li> <li>k. Cable ducts</li> <li>l. Power Connection cable:3pin plug with length of 1.3m</li> </ul>	1
10.	<ul> <li>I/O Interface module:</li> <li>a. 25 Pin D-Sub connector interface board for interfacing valves and actuators</li> <li>b. 25 Pin D-Sub cable for establishing connection between IO module and PLC control</li> </ul>	1
11.	<ul> <li>Valve Manifold with Field bus communication</li> <li>a. L x W x H :104.5x119.4x29.8 mm</li> <li>b. Grid spacing – 19 mm.</li> <li>c. Mountable valve port size 1/8"</li> <li>d. Silencers for reducing the dB level of exhausted air.</li> <li>e. 5/2 Double solenoid pilot operated valve:</li> <li>f. Material- Extruded Aluminum with anodized</li> <li>g. Voltage DC24V, Current consumption &lt;120mA</li> <li>Solenoid valve <ul> <li>a. Size – 1/8 "</li> <li>b. Design – Spool type</li> <li>c. Pressure range – 2 – 10 bar</li> <li>d. Flow rate – 450 l / min</li> <li>e. Manual override- Resetting</li> <li>f. Fitted with 1/8" flow control valve</li> </ul> </li> </ul>	1
12.	Cable duct and accessories: a. Wire duct size 45x25 b. Fastening screws	1

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#### **1.8 SORTING STATION WITH HMI**

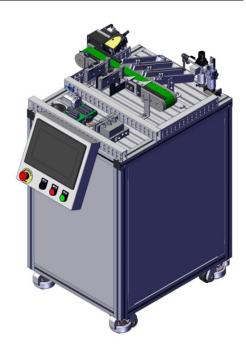
#### FEATURES

INDUSTRY

===

4.0

- DC Brushless conveyor
- Twin piston rod cylinder
- Inductive sensor
- Optical based RGB color sensor
- Valve terminal with Field bus communication
- HMI Control console
- Completely preassembled system
- Easy to use, and commission.
- Workbook with tasks and Solutions



#### APPLICATION

These Mechatronics systems are fully functional models of actual applications, mimicking hybrid, real life, industrial automation scenarios. A wide variety of project assignments and learning objectives help students to build hybrid systems by integrating important automation technologies, such as

- Pneumatics
- Electrical
- PLC
- Mechanical
- Sensors

#### **TECHNICAL SPECIFICATIONS**

Model	MMS4
Size (in cm)	54x64x110
Installation	Vertical
Ambient temperature	60°C Max.
Medium	Filtered Compressed air
Operating Pressure range (Bar)	6-8 bar
Operating Voltage +/- 10%	230V AC, 50HZ
Power consumption	180 W (224 VA)
Sensors and actuator operating voltage	24V, DC
Material of construction	Aluminum, mild steel, Plastic etc.





Series MMS4

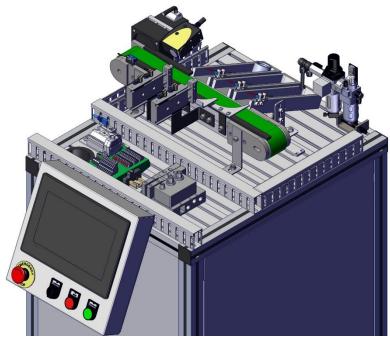
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#### FUNCTION

Sorting Station sorts the incoming work piece based on colour and material characteristics to appropriate slides.

The Sorting Station consists of the following.

- FRCLM module
- Sorting Conveyor module
- Valve module with Fieldbus communication
- I/O Interface Module
- Profile Table work bench
- PLC control
- HMI Control Console



The sorting station has 3 slides to sort the different materials and color of jobs that are arriving at this station. The sensors sense the presence of jobs at the start of the conveyor and also detect features of the jobs in order to start the conveyor and control the diversion of material in the appropriate slide. The pneumatically actuated sorting arrangements extend to intercept the work pieces into the appropriate slides. The station consists of anodized profile table, filter regulator and lubricator unit with pressure gauge, on/off valve quick push connections and couplings mounted with suitable mountings for easy assembly and disassembly.





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#### **SCOPE OF SUPPLY:**

S. No	Item with description	Qty
	Horizontal Aluminum profile table:	
	a. (L x W x H)- 540 x 640 x 790 mm	
	b. Aluminum profile	
	Tabletop profile – 40 x 160 mm	
	Supporting profile- 40 x 40 mm	
1.	c. Grid spacing (From slot to slot) – 40 mm	1
	d. Profile groove width – 8.3 mm	
	e. Leveling casters for quick setting and smooth movement	
	f. Profile plate connectors:	
	Length 55 mm, thickness 5mm	
	Mounting method M6 Socket head screw with M6 hammer head nut	
2.	I/O Interface module:	1
	a. 25 Pin D-Sub connector interface board for interfacing valves and actuators	
	b. 25 Pin D-Sub cable for establishing connection between IO module and PLC control	
3.	Valve Manifold with Field bus communication	
	a. L x W x H :104.5x119.4x29.8 mm	
	b. Grid spacing – 19 mm.	
	c. Mountable valve port size 1/8"	
	d. Silencers for reducing the dB level of exhausted air.	
	e. 5/2 Double solenoid pilot operated valve:	
	f. Material- Extruded Aluminum with anodized	
	g. Voltage DC24V, Current consumption <120mA	1
	Solenoid valve	
	a. Size – 1/8 "	
	b. Design – Spool type	
	c. Pressure range – 2 – 10 bar	
	d. Flow rate – 450 l / min	
	e. Manual override- Resetting	
	f. Fitted with 1/8" flow control valve	
4.	Filter Regulator Combination with Lubricator (FRL Unit) with pressure gauge & start up	
	valve:	
	a. Port size -1/4 inch	
	b. Flow rate – 500 l/min	
	c. Maximum supply pressure – 10 bar	
	d. Operating pressure- 6 bar	1
	e. Filtering element grade – 40 μm	
	f. Minimum operating flow – 12 l/min	
	g. Filter Bowl capacity – 9 ml	
	h. Lubricator Bowl capacity – 20 ml	
	i. Connection for tube 8 dia input and 8 dia output	





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	i Mounting - Socket head can screw with M6 hammer head put	
	<ul> <li>j. Mounting – Socket head cap screw with M6 hammer head nut</li> <li>Sorting Conveyor Module: <ul> <li>a. Flat belt conveyor with overall length of 500mm</li> <li>b. Conveyor to be driven by 24V DC motor of reputed make.</li> <li>c. Conveyor to be provided with electronic drive unit for regulating the speed, reversing the direction and other functions.</li> <li>d. Comprising of 2 pneumatic cylinders of dia 25 mm and stroke 40 mm</li> <li>e. Sorting slides for collecting the work piece on appropriate slides.</li> </ul> </li> <li>Color Sensor: <ul> <li>a. Sensing range: 15mm</li> <li>b. Supply Voltage and Current: 10 to 30V DC (10% max. ripple)</li> <li>c. Switch output: PNP, normally open/normally closed contact</li> <li>d. Output Protection: Protected against false pulse on power-up, short-circuit protected.</li> </ul> </li> </ul>	
5.	<ul> <li>e. Output rating: 100 mA</li> <li>Proximity sensor: <ul> <li>a. Type - Cylindrical inductive type</li> <li>b. Supply voltage -12 - 24V DC</li> <li>c. Sensing range - 8 mm</li> </ul> </li> <li>Diffuse Sensor: <ul> <li>a. Type: Infra-red</li> <li>b. Sensing range: 15mm</li> <li>c. Supply Voltage and Current: 10 to 30V DC (10% max. ripple) @ 20 mA max current</li> <li>d. Switch output: PNP, normally open/normally closed contact</li> <li>e. Output Protection: Protected against false pulse on power-up, short-circuit protected</li> </ul> </li> <li>RFID sensor: <ul> <li>a. Read/write distance :15mm(min)</li> <li>b. Supply Voltage:10 to 30V DC</li> <li>c. M8 Communication/ Power cable</li> </ul> </li> </ul>	1
6.	<ul> <li>HMI Control console:</li> <li>a. 10" HMI Make: Exor</li> <li>b. Cycle start push button –Green with illuminated.</li> <li>c. Auto /Manual selector switch -Black</li> <li>d. Home position push button –Red with illuminated</li> <li>e. Emergency button -Red</li> </ul>	1
7.	Cable duct and accessories: a. Wire duct size 45x25 b. Fastening screws	1
8.	<ul> <li>PLC control panel with DELTA PLC – DVP Series:</li> <li>a. Power supply: Input voltage :230/115 V AC (47 – 63 Hz), Output voltage: 24 V DC, short-circuit-proof Output current: Maximum 3A</li> <li>b. Miniature circuit breaker DC voltage with max.5A current rating</li> <li>c. Digital inputs-24, Digital outputs 16, Analog inputs 4, Ethernet interface 1 x TCP/IP, 10 Mbit/s</li> <li>d. Terminal blocks</li> </ul>	1





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- e. 25pin D-sub I/O data cable length 1.5 m, wire used 0.25 mm2.
  - f. Cable ducts
  - g. Power Connection cable:3pin plug with length of 1.3m
  - h. Opto- Coupler
  - i. IO link module
  - j. Number of Inputs, voltage(V): 2, 20-28VDC





Series MMS4

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#### 2. AUTONOMOUS MOBILE ROBOT (AMR) WITH COBOT

#### FEATURES

- Safety in collaborative applications
- Quick configuration
- Intelligent navigation system
- Works safely with people.
- High Accuracy Positioning System using Vision Camera
- Improve material trace ability.
- Easy to integrate with MES, ERP and WMS system.



(The above image is only for reference. The actual system may slightly differ from the image.)

#### **APPLICATION**

The AMR is used to demonstrate the material transportation, Assembly, Pick and place, Warehouse management & logistics in industries.

#### **TECHNICAL SPECIFICATIONS**

Model	-
AMR	
Make	Addverb / MiR
Size	920mm x 755mm x 300mm
AMR Payload	200 Kg
AMR Speed m/sec	2
Battery	22-30 V DC
Run Time	4 hours (Continuous)
Turning radius	On spot turning
Ambient temperature ( ºC )	5 to 40 ºC
Charging Power	230 V AC, 50 Hz



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User interface communication Wireless	802.11 a/b/g/n/ac	
Operating Voltage +/- 10%	22 to 30 V DC	
Power consumption	2.1 KW	
Other features	Safety laser scanners & Ultrasonic sensors Safety System: 1 Lidar sensor (mounted at the front), 3D Depth camera, bumper on front and back side, 2 emergency stop buttons Safety Sensor: 2D LIDAR Operational Mode : Auto / Manual Precision Docking: +/- 5mm Stopping Accuracy Docking : +/-20 mm Stopping Accuracy Positioning: +/-50 mm	
СОВОТ		
Make	Techman	
Cobot Payload in kg	4 kg	
Cobot Reach in mm	Max. 900 mm	
Number of axis	6	
Power supply	24V/2A	
IP Classification	IP54 Robot arm,IP32 Control Box	
Mounting Any angle Including table mounting, wall mounting Ceiling mounting		

#### FUNCTION

The Autonomous mobile robot is used for Autonomous material transportation in Smart manufacturing / Smart Factory environment.

The AMR station consists of the following.

- Cobot module with in-built vision system
- AMR module
- Electrical gripper module
- Controller module
- Storage module

The collaborative robot (COBOT) is mounted on top of an Automated Mobile Robot (AMR). The cobot has an in-built vision and payload capacity of 4 Kg. The cobot can be programmed using ROS or the TM Flow software. The AMR uses a LIDAR and two depth cameras to navigate using Natural Navigation. It has a payload of 200 kg. The AMR can be controlled using a Fleet Management System. The AMR can be deployed to different locations using REST Api communication through the Fleet Management System. The AMR can be integrated with Modular Manufacturing System (MMS4.0) and additive or subtractive manufacturing machines for simulation of complete smart factory system.



**Series MMS4** 

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#### 3. PLC SOFTWARE AND ACCESSORIES

Ordering No	-	
PLC Programming software		
Technical	specifications	
Make	Siemens TIA Portal Basic,	
License	1 User each	e de la constante de la consta
Version	Latest	instic .
Packing	CD / OSD	
PLC programming cable		
Technical	specifications	
Make	Phoenix	
Cable	RJ45 to RJ45	
Length	5meter	
Quantity	1 Nos	W

#### 4. TECHNICAL DOCUMENTS

#### **FEATURES**

- Conforms to DIN ISO 1219-1
- Includes Pneumatic & Electrical circuit, positional sketch, assembly procedure, installation procedure, technical specifications of components and troubleshooting etc.
- Available for all stations & combinations
- Packed with 4 ring binder.



#### APPLICATION

Technical document enables user to understand the technical information like Pneumatic & Electrical circuit, positional sketch, assembly procedure, and installation procedure, technical specifications of components and troubleshooting etc. of the Modular manufacturing system.

S.no	Description	
1	Technical Document for Feeder station with HMI	1
2	Technical Document for Inspection station with HMI	1
3	Technical Document for Buffer station with HMI	1
4	Technical Document for Process station with HMI	1
5	Technical Document for Robot station with HMI	1





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6	6 Technical Document for Assembly station with HMI	
7	Technical Document for Sorting station with HMI	1
8	Technical Document for Combination stations	1

#### 5. WORK PIECE SET

Ordering code		MMS-WP-03-00	
		Technical Specificati	on
Туре	Inbuilt with RFID tag		
Work piece Approved	Diameter	39.5mm	
	Height	27mm	
Work piece Rejected	Diameter	39.5mm	
	Height	23.5mm	
Aluminium Work Piece - Approved		1set (6nos)	
Delrin Work Piece - Approved		1set (6nos)	
Hylum Work Piece - Approved		1set (6nos)	
Rejection work piece –		6 no's (Each 2nos)	
Aluminium, Delrin & Hylum			
Digital cap Approved		18 no's	
Digital cap Rejected		6no's	1





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#### 6. SMART MANUFACTURING EXECUTION SYSTEM

#### **FEATURES**

- Production Monitoring
- Overall Equipment Effectiveness OEE
- Condition Monitoring
- Order Management
- Energy Management
- Management Information System
- Maintanence

#### Application

The SMES4.0 application is a Manufacturing Execution System, which establishes the communication between Operational technology (OT) and Information Technology (IT) for the complete value chain management of the Smart manufacturing System. It is provided on SaaS (Software as a Service) platform with yearly subscription.







Series MMS4

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### 7. JANATICS AUGMENTED REALITY APPLICATION- JARA4.0

#### FEATURES

- Detects machine without any identification marks like QR code.
- Displays the real time machine status and error notification for machine monitoring and diagnostics.
- Provides online user manual and machine assembly & dismantling procedure.
- Provides user to generate machine report.
- Possible to self-create the error notifications for learning purposes.
- It is compatible to mobile gadgets iOS & wearable gadget.

#### APPLICATION

Janatics AR app allows users to create and access Augmented Reality experiences of the Modular Manufacturing System on your tablet or smartphone. Janatics AR application is freely downloadable from Apple store.

Janatics AR app displays real time machine data, the troubleshooting procedure in the form of digital documents and Videos and Machine downtime report. Users can also configure and position the real time data variables to be displayed and integrate them with products like modular manufacturing system.

